

## Homework Assignment #1

1. KFCS 1.3.1
  2. KFCS 1.4.1
  3. KFCS 1.5.4, plus the following:
    - (g) What is the real part of  $\mathbf{A} = \text{Re}(\mathbf{A})$ ?
    - (h) What is the imaginary part of  $\mathbf{B} = \text{Im}(\mathbf{B})$ ?
    - (i) What is the phase of  $\mathbf{B}$ ?
  4. KFCS 1.5.3, plus the following:
    - (f) What is the real part of  $\mathbf{A} = \text{Re}(\mathbf{A})$ ?
  5. KFCS 1.6.1
  6. KFCS 1.7.1. plus the following:
    - (c) Is the angular frequency that maximizes the acceleration calculated in part (b) the resonant frequency?
    - (d) What is the angular frequency that maximizes particle velocity? Is this the resonance frequency?
- Hint: Prior to maximizing the velocity and acceleration by setting their derivatives w.r.t. frequency equal to zero, find the real magnitude of the velocity and acceleration. You don't need the phase because that term and the time dependent exponential can be no bigger than one.

SHM

## PROBLEM 1.3.1

Note Title

8/22/2010

GIVEN : SHO FREQUENCY =  $\omega_0$ , AT  $t = \frac{T}{2}$   $x(t) = +U$

FIND :  $x(t)$

SOLUTION 1:  $x(t) = A \cos(\omega_0 t + \phi)$  (EQN 1.3.2)

$$u(t) = \frac{dx}{dt} = -A \omega_0 \sin(\omega_0 t + \phi)$$

$$t = \frac{T}{2} \quad x\left(\frac{T}{2}\right) = A \cos\left(\omega_0 \frac{T}{2} + \phi\right) = A \cos\left(\frac{2\pi T}{T} \frac{T}{2} + \phi\right) \\ = A \cos(\pi + \phi) = \text{NOT SPECIFIED (DIRECTLY)}$$

$$u\left(\frac{T}{2}\right) = -A \omega_0 \sin\left(\omega_0 \frac{T}{2} + \phi\right) = -A \omega_0 \sin\left(\frac{2\pi T}{T} \frac{T}{2} + \phi\right) \\ = -A \omega_0 \sin(\pi + \phi) = +U$$

$$\sin(\pi + \phi) = -1 \quad \rightarrow \quad A \omega_0 = U$$

$$(\text{pick one}) \quad \pi + \phi = -\frac{\pi}{2}, \boxed{\frac{3\pi}{2}}, \frac{7\pi}{2}, \dots \quad A = \frac{U}{\omega_0}$$

$\phi = \frac{\pi}{2}$   
 (OTHER VALUES FOR  
 $\phi$  ARE ALSO CORRECT)

$$\therefore \boxed{x(t) = \frac{U}{\omega_0} \cos\left(\omega_0 t + \frac{\pi}{2}\right)}$$

SOLUTION 2:  $x(t) = A_1 \cos \omega_0 t + A_2 \sin \omega_0 t$  (EQN 1.2.8)

$$u(t) = -A_1 \omega_0 \sin \omega_0 t + A_2 \omega_0 \cos \omega_0 t$$

$$\begin{aligned}
 u\left(\frac{T}{2}\right) &= -A_1 \omega_0 \sin\left(\omega_0 \frac{T}{2}\right) + A_2 \omega_0 \cos\left(\omega_0 \frac{T}{2}\right) \\
 &= -A_1 \omega_0 \sin\left(\frac{2\pi}{T} \frac{T}{2}\right) + A_2 \omega_0 \cos\left(\frac{2\pi}{T} \frac{T}{2}\right) \\
 &= -A_1 \omega_0 \sin^0(\pi) + A_2 \omega_0 \overset{-1}{\cos}(\pi) = U \\
 A_2 &= \frac{-U}{\omega_0}
 \end{aligned}$$

BUT WHAT IS  $A_1$ ? EARLIER I SAID  
 $\chi\left(\frac{T}{2}\right)$  WAS NOT SPECIFIED. THIS IS  
NOT REALLY TRUE. IF  $u\left(\frac{T}{2}\right) = \text{MAX}$ ,  
 $\chi\left(\frac{T}{2}\right) = 0$ . SO IN SOLUTION 1,

$$\cos(\pi + \phi) = 0 \Rightarrow \pi + \phi = -\frac{\pi}{2}, \frac{\pi}{2}, \boxed{\frac{3\pi}{2}}, \frac{5\pi}{2}, \dots$$

$$\phi = \frac{\pi}{2} \text{ AGAIN } \checkmark$$

In SOLUTION 2,

$$\chi(t) = A_1 \cos \omega_0 t - \frac{U}{\omega_0} \sin \omega_0 t$$

$$\chi\left(\frac{T}{2}\right) = A_1 \cos\left(\frac{2\pi}{T} \frac{T}{2}\right) - \frac{U}{\omega_0} \sin\left(\frac{2\pi}{T} \frac{T}{2}\right) = 0$$

$$A_1 \cos(\pi) = 0 \Rightarrow A_1 = 0$$

$$\boxed{\chi(t) = -\frac{U}{\omega_0} \sin \omega_0 t}$$

THIS SHOWS  $\cos(\theta + \frac{\pi}{2}) = -\sin \theta$  !!

# SHM ENERGY

1.4.1

Note Title

8/22/2010

Show:  $E_{k(\max)} = E_{p(\max)}$  For UNDAMPED SHO

$$E_k = \frac{1}{2}mu^2 \quad E_p = \frac{1}{2}sx^2$$

$$\text{USE } x = A \cos(\omega_0 t + \phi)$$

$$u = \frac{dx}{dt} = -A\omega_0 \sin(\omega_0 t + \phi)$$

$$E_k = \frac{1}{2}m(-A\omega_0 \sin(\omega_0 t + \phi))^2 \quad E_p = \frac{1}{2}s(A \cos(\omega_0 t + \phi))^2$$

$$= \frac{1}{2}mA^2\omega_0^2 \sin^2(\omega_0 t + \phi) \quad E_p = \frac{1}{2}sA^2 \cos^2(\omega_0 t + \phi)$$

$$E_{k(\max)} = \frac{1}{2}mA^2\omega_0^2 \quad E_{p(\max)} = \frac{1}{2}sA^2$$

(SINCE THE MAX VALUE OF  $\cos$  &  $\sin$  ARE 1)

$$\text{BUT } \omega_0^2 = \frac{s}{m}$$

$$E_{k(\max)} = \frac{1}{2}mA^2\left(\frac{s}{m}\right) = \frac{1}{2}sA^2 = E_{p(\max)}$$

Q.E.D.

# COMPLEX NUMBERS CARTESIAN

1.5.4

Note Title

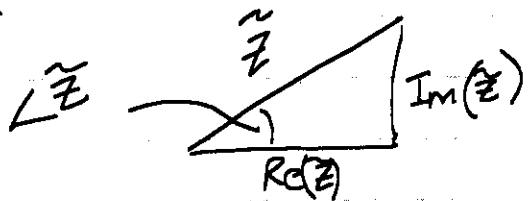
8/22/2010

GIVEN:  $\tilde{A} = x + jy$        $\tilde{B} = X + jY$

FIND:  $|\tilde{A}|$ ,  $|\tilde{B}|$ ,  $|\tilde{A}\tilde{B}|$ ,  $\operatorname{Re}(\tilde{A}\tilde{B})$ , PHASE OF  $\tilde{A}\tilde{B}$   
 $\operatorname{Re}\left(\frac{\tilde{A}}{\tilde{B}}\right)$ ,  $\operatorname{Re}(\tilde{A})$ ,  $\operatorname{Im}(\tilde{B})$ ,  $\angle \tilde{B}$

$$\boxed{|\tilde{A}| = (x^2 + y^2)^{1/2}}$$

$$\boxed{|\tilde{B}| = (X^2 + Y^2)^{1/2}}$$



$$\begin{aligned}\tilde{A}\tilde{B} &= (x + jy)(X + jY) = xX + jxY + jyX - yY \\ &= xX - yY + j(xY + yX)\end{aligned}$$

$$\begin{aligned}|\tilde{A}\tilde{B}| &= ((xX - yY)^2 + (xY + yX)^2)^{1/2} \\ &= (x^2X^2 + y^2Y^2 - 2xyXY + x^2Y^2 + y^2X^2 + 2xyXY)^{1/2} \\ &= ((x^2X^2 + y^2Y^2 + x^2Y^2 + y^2X^2)^{1/2})\end{aligned}$$

$$\operatorname{Re}(\tilde{A}\tilde{B}) = xX - yY$$

$$\angle \tilde{A}\tilde{B} = \tan^{-1}\left(\frac{\operatorname{Im}(\tilde{A}\tilde{B})}{\operatorname{Re}(\tilde{A}\tilde{B})}\right) = \tan^{-1}\left(\frac{xY + yX}{xX - yY}\right)$$

$$\frac{\tilde{A}}{\tilde{B}} = \frac{x + jy}{x + jy} \left( \frac{x - jy}{x - jy} \right) = \frac{xx + yy + j(yx - xy)}{x^2 + y^2}$$

$$\boxed{\operatorname{Re}\left(\frac{\tilde{A}}{\tilde{B}}\right) = \frac{xx + yy}{x^2 + y^2}}$$

$$\boxed{\operatorname{Re}(\tilde{A}) = x}$$

$$\boxed{\operatorname{Im}(\tilde{B}) = y}$$

$$\boxed{\angle \tilde{B} = \tan^{-1}\left(\frac{y}{x}\right)}$$

# COMPLEX NUMBERS POLAR

1.5.3

Note Title

8/22/2010

GIVEN:  $\tilde{A} = A e^{j(\omega t + \theta)}$        $\tilde{B} = B e^{j(\omega t + \phi)}$

FIND:  $\operatorname{Re}(\tilde{A}\tilde{B})$ ,  $\operatorname{Re}\left(\frac{\tilde{A}}{\tilde{B}}\right)$ ,  $\operatorname{Re}(\tilde{A})\operatorname{Re}(\tilde{B})$ ,  $\angle \tilde{A}\tilde{B}$   
 $\angle \frac{\tilde{A}}{\tilde{B}}$ ,  $|\tilde{A}|$ ,

$$\tilde{A}\tilde{B} = AB e^{j(\omega t + \theta)} e^{j(\omega t + \phi)} = AB e^{j(2\omega t + \theta + \phi)}$$

$$\boxed{\operatorname{Re}(\tilde{A}\tilde{B}) = AB \cos(2\omega t + \theta + \phi)}$$

$$\frac{\tilde{A}}{\tilde{B}} = \frac{A e^{j(\omega t + \theta)}}{B e^{j(\omega t + \phi)}} = \frac{A}{B} e^{j(\theta - \phi)}$$

$$\boxed{\operatorname{Re}\left(\frac{\tilde{A}}{\tilde{B}}\right) = \frac{A}{B} \cos(\theta - \phi)}$$

$$\begin{aligned} \operatorname{Re}(\tilde{A}) \operatorname{Re}(\tilde{B}) &= \frac{A \cos(\omega t + \theta) B \cos(\omega t + \phi)}{AB \cos(\omega t + \theta) \cos(\omega t + \phi)} \\ &\neq \operatorname{Re}(\tilde{A}\tilde{B}) \end{aligned}$$

$$\boxed{\angle \tilde{A}\tilde{B} = 2\omega t + \theta + \phi}$$

$$\boxed{\angle \frac{\tilde{A}}{\tilde{B}} = \theta - \phi}$$

$$\boxed{|\tilde{A}| = A}$$

$$\operatorname{Re}(\hat{A}) = \boxed{A \cos(\omega t + \Theta)}$$

# DAMPED OSCILLATOR

1.6.1

Note Title

8/22/2010

GIVEN:  $m = .5 \text{ kg}$        $\Delta m = .2 \text{ kg} \Leftrightarrow \Delta x = .04 \text{ m}$   
 $T = 1 \text{ s}$        $x(t=0) = .04 \text{ m}$        $u(t=0) = 0$

FIND:  $R_m$ ,  $\omega_d$ ,  $A$  &  $\phi$

WE COULD JUST START WITH EQNS 1.6.8 & 1.6.9  
 BUT IT IS HELPFUL TO SEE WHERE THEY  
 CAME FROM.

THE EOM FROM NZL       $m \frac{d^2 \tilde{x}}{dt^2} + R_m \frac{dx}{dt} + S \tilde{x} = 0$

ASSUME       $\tilde{x} = \tilde{A} e^{\gamma t}$

$$\frac{d\tilde{x}}{dt} = \gamma \tilde{A} e^{\gamma t}$$

$$\frac{d^2 \tilde{x}}{dt^2} = \gamma^2 \tilde{A} e^{\gamma t}$$

$$m \gamma^2 \tilde{A} e^{\gamma t} + R_m \gamma \tilde{A} e^{\gamma t} + S \tilde{A} e^{\gamma t} = 0$$

$$m \gamma^2 + R_m \gamma + S = 0$$

$$\gamma = \frac{-R_m \pm \sqrt{R_m^2 - 4ms}}{2m} = \frac{-R_m \pm \sqrt{\left(\frac{R_m}{2m}\right)^2 - \frac{s}{m}}}{2m}$$

LET  $B = \frac{R_m}{2m}$  & RECALL  $\omega_0^2 = \frac{s}{m}$

$$\gamma = -B \pm \sqrt{B^2 - \omega_0^2}$$

For The UNDERDAMPED CASE,  $\omega_0 > \beta$

$$\gamma = -\beta \pm j\sqrt{\omega_0^2 - \beta^2} = -\beta \pm j\omega_d$$

WHERE  $\boxed{\omega_d = \sqrt{\omega_0^2 - \beta^2}}$

$$\tilde{x} = \tilde{A}_1 e^{-\beta t} e^{j\omega_d t} + \tilde{A}_2 e^{-\beta t} e^{-j\omega_d t}$$

$$\tilde{A}_1 = \frac{A}{2} e^{j\phi} \quad \tilde{A}_2 = \frac{A}{2} e^{-j\phi}$$

$$= A e^{-\beta t} \left[ \frac{e^{j\phi} e^{j\omega_d t} + e^{-j\phi} e^{-j\omega_d t}}{2} \right]$$

$$= \boxed{A e^{-\beta t} \cos(\omega_d t + \phi)} \quad (\text{EQN 1.6.13})$$

$$S = \frac{\Delta F}{\Delta x} = \frac{\Delta mg}{\Delta x} = \frac{(2 \text{ kg})(9.8 \text{ m/s}^2)}{0.09 \text{ m}} = 49 \frac{\text{N}}{\text{m}}$$

$$\beta = \frac{1}{T} = \frac{1}{1 \text{ s}} = 1 \text{ s}^{-1}$$

$$\beta = \frac{R_m}{2m} \Rightarrow R_m = 2m\beta = 2(0.5 \text{ kg})(1 \text{ s}^{-1}) = \boxed{1 \frac{\text{kg}}{\text{s}}}$$

$$\omega_0^2 = \frac{S}{m} = \frac{49 \frac{\text{N}}{\text{m}}}{0.5 \text{ kg}} = 98 \text{ s}^{-2}$$

$$\omega_d^2 = \omega_0^2 - \beta^2 = 98 \text{ s}^{-2} - 1 \text{ s}^{-2} = 97 \text{ s}^{-2}$$

$$\omega_d = \sqrt{97 \text{ s}^{-2}} = \boxed{9.85 \text{ s}^{-1}}$$

$$x(t=0) = .04 \text{ m} = A(e^\circ) \cos(0 + \phi)$$

$$.04 = A \cos \phi$$

$$u = \frac{dx}{dt} = Ae^{-\beta t}(-\omega_d) \sin(\omega_d t + \phi) + A(-\beta)e^{-\beta t} \cos(\omega_d t + \phi)$$

$$u(t=0) = 0 = A(e^\circ)(-\omega_d) \sin \phi + A(-\beta)e^\circ \cos \phi = 0$$

$$-\omega_d \sin \phi = \beta \cos \phi$$

$$\frac{\sin \phi}{\cos \phi} = \tan \phi = \frac{-\beta}{\omega_d} = \frac{-157}{9.85} = -15.8$$

$$\phi = \tan^{-1}\left(\frac{1}{9.85}\right) = [-.101 \text{ rad}] = -5.8^\circ$$

$$A = \frac{.04}{\cos(-.101 \text{ rad})} = [.0402 \text{ m}]$$

# DAMPED FORCED OSCILLATOR

1.7.1

Note Title

8/22/2010

GIVEN: DAMPED FORCED OSCILLATOR  $F_{\text{app}} = F \cos \omega t$

FIND:  $a(t)$ ,  $\omega$  FOR  $a_{\max}$   
 $\omega$  FOR  $u_{\max}$   
 $\omega_{\text{resonance}}$

REAL  
PART

YOU COULD START WITH EQN 1.7.5 BUT LET'S  
 REVIEW IT'S ORIGIN

E.O.M From NZL  $m \frac{d^2 \tilde{x}}{dt^2} + R_m \frac{dx}{dt} + s x = F e^{j\omega t}$

ASSUME

$$\tilde{x} = \tilde{A} e^{j\omega t}$$

$$\frac{dx}{dt} = j\omega \tilde{A} e^{j\omega t}$$

$$\frac{d^2x}{dt^2} = -\omega^2 \tilde{A} e^{j\omega t}$$

$$(-m\omega^2 \tilde{A} + jR_m \omega \tilde{A} + s \tilde{A}) e^{j\omega t} = F e^{j\omega t}$$

$$\tilde{A} = \frac{F}{-m\omega^2 + s + jR_m \omega}$$

REARRANGING

$$\tilde{A} = \frac{F}{j\omega(R_m + j\omega m - j\frac{\Sigma}{\omega})}$$
$$= \frac{F}{j\omega(R_m + j(\omega m - \frac{\Sigma}{\omega}))}$$

$$\tilde{x} = \tilde{A} e^{j\omega t} = \frac{F e^{j\omega t}}{j\omega(R_m + j(\omega m - \frac{\Sigma}{\omega}))}$$

$$\tilde{u} = \frac{d\tilde{x}}{dt} = \frac{F e^{j\omega t}}{R_m + j(\omega m - \frac{\Sigma}{\omega})}$$

IDENTIFY  $\tilde{Z}_m = R_m + j(\omega m - \frac{\Sigma}{\omega})$

BY DEFINITION  $\omega_{res} m - \frac{\Sigma}{\omega_{res}} = 0$

$$\omega_{res} = \sqrt{\frac{\Sigma}{m}}$$

$$\boxed{\tilde{a} = \frac{d\tilde{u}}{dt} = \frac{j\omega F e^{j\omega t}}{R_m + j(\omega m - \frac{\Sigma}{\omega})}}$$

THIS IS A SIMPLE LOOKING RESULT, BUT  
WE WANT A REAL FUNCTION TO MAXIMIZE

i.e.  $\tilde{a} = a_0 e^{j\theta_a} e^{j\omega t}$

THEN  $\frac{da_0}{dw} = 0$  WILL GIVE THE  
FREQ FOR MAX Q

$$\begin{aligned}
 a_0 &= \left( \frac{j\omega F}{R_m + j(\omega_m - \frac{\omega}{\omega})} \right) \left[ \frac{j\omega F}{R_m + j(\omega_m - \frac{\omega}{\omega})} \right]^* \Big)^{\frac{1}{2}} \\
 &= \left( \frac{(j\omega F)(-j\omega F)}{\left[ R_m + j\left(\omega_m - \frac{\omega}{\omega}\right) \right] \left[ R_m - j\left(\omega_m - \frac{\omega}{\omega}\right) \right]} \right)^{\frac{1}{2}} \\
 &= \left( \frac{\omega^2 F^2}{R_m^2 + \left(\omega_m - \frac{\omega}{\omega}\right)^2} \right)^{\frac{1}{2}} = \frac{\omega F}{\left( R^2 + \left(\omega_m - \frac{\omega}{\omega}\right)^2 \right)^{\frac{1}{2}}} \\
 &= \omega F \left( R_m^2 + \left(\omega_m - \frac{\omega}{\omega}\right)^2 \right)^{-\frac{1}{2}}
 \end{aligned}$$

$$\begin{aligned}
 \frac{da_0}{dw} &= w \cancel{\Gamma}\left(-\frac{1}{2}\right) \left(R_m^2 + (wm - s\omega^{-1})^2\right)^{-\frac{3}{2}} \cancel{\chi}(wm - s\omega^{-1})(m + s\omega^{-2}) \\
 &\quad + \cancel{\Gamma}\left(R_m^2 + \left(wm - \frac{s}{\omega}\right)^2\right)^{-\frac{1}{2}} = 0 \\
 &= -w \left(wm - \frac{s}{\omega}\right) \left(m + \frac{s}{\omega^2}\right) \\
 &\quad \frac{1}{\left(R_m^2 + (wm - \frac{s}{\omega})^2\right)^{\frac{3}{2}}} + \frac{1}{\left(R_m^2 + (wm - \frac{s}{\omega})^2\right)^{\frac{1}{2}}} \\
 &= -\frac{w \left(wm - \frac{s}{\omega}\right) \left(m + \frac{s}{\omega^2}\right)}{\left(R_m^2 + (wm - \frac{s}{\omega})^2\right)^{\frac{3}{2}}} + \frac{R_m^2 + (wm - \frac{s}{\omega})^2}{\left(R_m^2 + (wm - \frac{s}{\omega})^2\right)^{\frac{1}{2}}} \\
 &= \frac{\left(wm - \frac{s}{\omega}\right) \left(-wm - \frac{s}{\omega}\right) + R_m^2 + (wm - \frac{s}{\omega})^2}{\left(R_m^2 + (wm - \frac{s}{\omega})^2\right)^{\frac{3}{2}}}
 \end{aligned}$$

$$0 = -\cancel{w^2 R_m^2} - \cancel{ws} + \cancel{ws} + \frac{s^2}{\omega^2} + R_m^2 + \cancel{w^2 R_m^2} - 2ms + \frac{s^2}{\omega^2}$$

$$0 = \frac{2s^2}{\omega^2} - 2ms + R_m^2$$

$$\frac{2s^2}{\omega^2} = 2ms - R_m^2 \quad \omega^2 = \frac{2s^2}{2ms - R_m^2}$$

$$\omega = \sqrt{\frac{2s^2}{2ms - R_m^2}} \quad \begin{matrix} (\text{NOT } \omega_{\text{res}} \\ \text{unless } R_m = 0) \end{matrix}$$

$$\omega = \sqrt{\frac{8\zeta^2}{8m\zeta(1 - \frac{R_m^2}{Z_m s})}} = \sqrt{\frac{s}{m}} \left(1 - \frac{R_m^2}{Z_m s}\right)^{-\frac{1}{2}}$$

$$= \omega_{res} \left(1 - \frac{R_m^2}{Z_m s}\right)^{-\frac{1}{2}}$$

FOLLOWING THE SAME APPROACH FOR VELOCITY

$$\tilde{u} = \frac{Fe^{j\omega t}}{R_m + j(\omega_m - \frac{s}{\omega})} = u_0 e^{jtG_{u_0}} e^{j\omega t}$$

$$u_0 = \left[ \frac{F}{R_m + j(\omega_m - \frac{s}{\omega})} \left( \frac{F}{R_m - j(\omega_m - \frac{s}{\omega})} \right) \right]^{\frac{1}{2}} = \left[ \frac{F^2}{R_m^2 + (\omega_m - \frac{s}{\omega})^2} \right]^{\frac{1}{2}}$$

$$= F \left( R_m^2 + (\omega_m - \frac{s}{\omega})^2 \right)^{-\frac{1}{2}}$$

$$\frac{du_0}{d\omega} = F \left( -\frac{1}{2} \right) \left( R_m^2 + (\omega_m - \frac{s}{\omega})^2 \right)^{-\frac{3}{2}} f \left( \omega_m - \frac{s}{\omega} \right) \left( m + \frac{s}{\omega^2} \right)$$

$$0 = \left( \omega_m - \frac{s}{\omega} \right) \left( m + \frac{s}{\omega^2} \right) = \omega_m^2 + \frac{sm}{\omega} - \frac{sh}{\omega} - \frac{s^2}{\omega^3}$$

$$\omega_m^2 = \frac{s^2}{\omega^3}$$

$$\omega^4 = \frac{s^2}{m^2} \Rightarrow \omega^2 = \frac{s}{m} = \omega_{res}^2$$