

## Summary of Formulae for Collision Problems—C.E. Mungan, Fall 2000

We assume that we have an isolated system of two objects and that we are given  $m_1$ ,  $m_2$ ,  $\mathbf{v}_{1i}$ , and  $\mathbf{v}_{2i}$  and are trying to solve for  $\mathbf{v}_{1f}$  and  $\mathbf{v}_{2f}$ . (If instead you are given some or all of the information about the final velocities, you can rearrange the following equations appropriately.) In the case of a perfectly inelastic collision,  $\mathbf{v}_f \equiv \mathbf{v}_{1f} = \mathbf{v}_{2f}$ .

### 1D Perfectly Inelastic

Conservation of linear momentum:

$$v_{fx} = \frac{m_1 v_{1ix} + m_2 v_{2ix}}{m_1 + m_2} \quad (1)'$$

### 1D Elastic

Conservation of linear momentum:

$$m_1 v_{1ix} + m_2 v_{2ix} = m_1 v_{1fx} + m_2 v_{2fx} \quad (1)$$

Elastic collision equation (only valid before and after the collision):

$$v_{1ix} + v_{1fx} = v_{2ix} + v_{2fx} \quad (2)'$$

Solve these two linear equations simultaneously to get  $v_{1fx}$  and  $v_{2fx}$ , as given by Serway Eqs. (8.20) and (8.21) with  $x$  subscripts added to every velocity. Make sure you know how to do this! During the collision, Eq. (1) still holds, but Eq. (2)' must be replaced by conservation of mechanical energy (where  $U$  is the interactional potential energy):

$$\frac{1}{2} m_1 v_{1i}^2 + \frac{1}{2} m_2 v_{2i}^2 + U_i = \frac{1}{2} m_1 v_{1f}^2 + \frac{1}{2} m_2 v_{2f}^2 + U_f \quad (2)''$$

### 1D Imperfectly Inelastic

Conservation of linear momentum:

$$m_1 v_{1ix} + m_2 v_{2ix} = m_1 v_{1fx} + m_2 v_{2fx} \quad (1)$$

In addition, you need to be given directly or implicitly either  $v_{1fx}$  or  $v_{2fx}$ , in order to be able to solve Eq. (1) for the other.

### 2D Perfectly Inelastic

Conservation of linear momentum:

$$v_{fx} = \frac{m_1 v_{1ix} + m_2 v_{2ix}}{m_1 + m_2} \quad \text{and} \quad v_{fy} = \frac{m_1 v_{1iy} + m_2 v_{2iy}}{m_1 + m_2} \quad (1)'$$

## 2D Elastic

Conservation of linear momentum:

$$m_1 v_{1ix} + m_2 v_{2ix} = m_1 v_{1fx} + m_2 v_{2fx} \quad \text{and} \quad m_1 v_{1iy} + m_2 v_{2iy} = m_1 v_{1fy} + m_2 v_{2fy} \quad (1)$$

Conservation of mechanical energy:

$$\frac{1}{2} m_1 v_{1i}^2 + \frac{1}{2} m_2 v_{2i}^2 + U_i = \frac{1}{2} m_1 v_{1f}^2 + \frac{1}{2} m_2 v_{2f}^2 + U_f \quad (2)''$$

Before and after the collision, the interactional potential energy is zero so that (2)'' simplifies to:

$$\frac{1}{2} m_1 v_{1i}^2 + \frac{1}{2} m_2 v_{2i}^2 = \frac{1}{2} m_1 v_{1f}^2 + \frac{1}{2} m_2 v_{2f}^2 \quad (2)$$

In addition, you need to be given directly or implicitly  $v_{1fx}$ ,  $v_{2fx}$ ,  $v_{1fy}$ ,  $v_{2fy}$ ,  $v_{1f}$ ,  $v_{2f}$ ,  $\theta_{1f}$ , or  $\theta_{2f}$ . Using this together with Eqs. (1) and (2) allows you to solve simultaneously for all the others.

## 2D Imperfectly Inelastic

Conservation of linear momentum:

$$m_1 v_{1ix} + m_2 v_{2ix} = m_1 v_{1fx} + m_2 v_{2fx} \quad \text{and} \quad m_1 v_{1iy} + m_2 v_{2iy} = m_1 v_{1fy} + m_2 v_{2fy} \quad (1)$$

In addition, you need to be given directly or implicitly two of ( $v_{1fx}$  or  $v_{2fx}$ ), ( $v_{1fy}$  or  $v_{2fy}$ ),  $v_{1f}$ ,  $v_{2f}$ ,  $\theta_{1f}$ , and  $\theta_{2f}$ .